

DOCUMENT TITLE:Operation & Maintenance Manual for Class 5 GearboxPROJECT TITLE:8.2. ISO-5-Mech.InterfacesPROJECT:600145DOCUMENT NUMBER:600145-TD-0002REV:01NUMBER OF PAGES:12DATE:04.05.2023

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### OBJECTIVE

The objective of this document is to present a comprehensive technical description of the Blue Logic Class 5 Gearbox. Relevant technical aspects for information and familiarization are covered as well as detailed technical data. For further information reference is made to drawing BA7652 Class 5 Gearbox.

### ABSTRACT

The Blue Logic Gear Box CI. 5 is designed in accordance with ISO/API, and the purpose is to enable operation of equipment with Class 5 interface using a torque tool with Class 4 output interface.

#### **REVISION CHANGE/RECORD**

REV	REASON FOR REVISION/ DESCRIPTION OF CHANGES		
01	Issued for Use		



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### 1. INTRODUCTION

The Class 5 Gearbox is designed to enable operation of Class 5 interfaces using a Class 4 torque tool for maximum flexibility at minimum cost.

The gearbox can be delivered as a complete kit, BB2406, including required components to adapt the tool to the interfaces as described above.

The Gearboxes are available as 6,7kNm (standard version) and 10,8kNm versions.

#### 1.1. DOCUMENT USE

This document shall be used as a general information for all aspects related to safe use, installation, removal, maintenance, and storage of the Class 5 Gearbox.

#### 1.2. REFERENCES

Latest version of the following documents

ld.	Doc. No	Originator	Document Title
/01/	BA7652	Blue Logic	Class 5 Gear Box
/02/	BB2406	Blue Logic	Gear Box Cl. 5 Arrangement (Kit)

#### 1.3. ABBREVIATIONS

ROV	Remotely Operated Vehicle			
HPU	Hydraulic Power Unit			
FAT	Factory Acceptance Test			
TT	Torque Tool			



### 2. TECHNICAL DESCRIPTION

#### 2.1. GENERAL

The gearbox is designed to be a compact tool with low submerged weight to enable efficient ROV intervention. As base case, the gearbox is intended to be used as a stand-alone unit for installation in Class 5 interfaces. Once installed, the Class 4 torque tool, hereafter referred to as TT, shall be inserted in the Class 4 interface of the gearbox. The unit is then ready for operation.

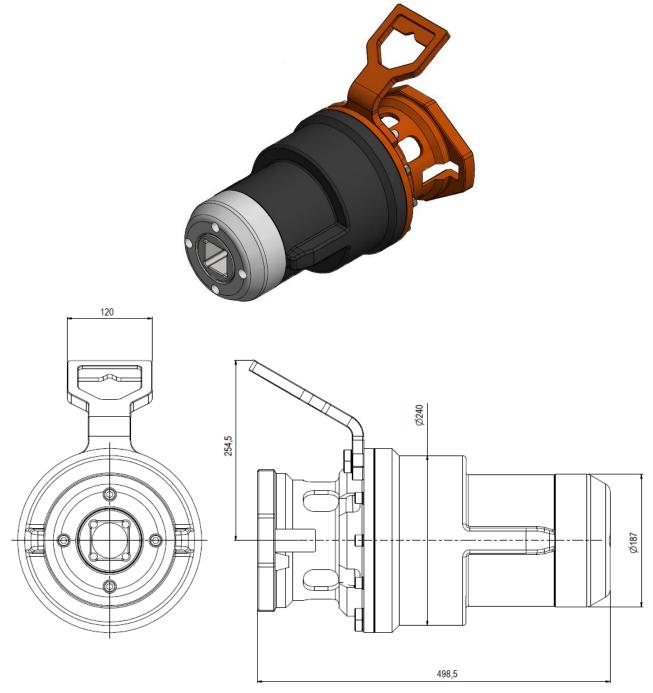
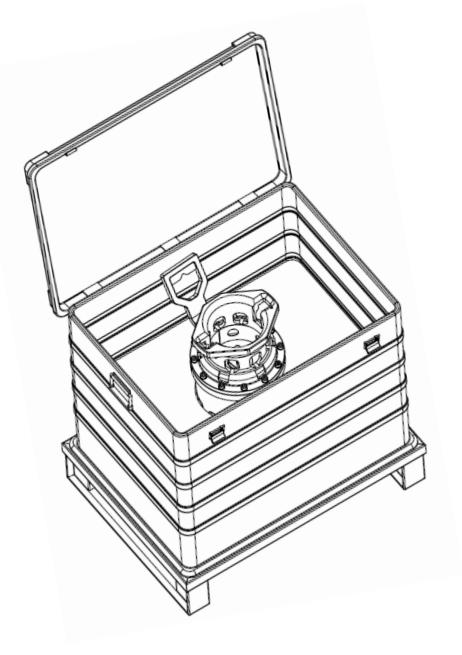
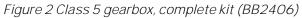


Figure 1, Cl.5 gearbox

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The gearbox is delivered in a transport box, containing required accessories and spares.



#### 2.2. INTERFACES

2.2.1. Mechanical Interface Torque Input:

- ISO/API Class 4

Torque Output:

- ISO/API Class 5

ROV Interface:

- ROV D-handle

#### 2.2.2. Hydraulic Interface

The gearbox is all-mechanical, but the housing is pressure compensated using an oil-filled ½" Tygon compensator hose. Blind fitting at the end of the hose to be pulled out for filling/draining of compensation hose. Make sure to evacuate all air when filling with oil. Gear-oil: Q8 T 65 75W-90.

#### 2.3. MATERIAL SELECTION

The gearbox is mainly constructed in anodized Aluminium, and designed for intervention, i.e. not permanent installation

#### 2.4. TECHNICAL DATA

Overall dimensions	Ø260 x 499 mm
Weight in air	41,4 kg
Weight in water	28,6 kg
Pressure rating	300 bar
Max water depth	3 000 m
Max output, gear ratio 1:2,5	6,7 kNm
Max output, gear ratio 1:3,78	10 kNm
Gear-oil	Q8 T 65 75W-90



### 3. OPERATION

#### 3.1. PREPARATIONS

Prior to operation, the following actions shall be carried out.

ID	Description
1	Check the gearbox for damages.
2	Verify correct output interface selected. Replace output interface if required, ref. section 3.4.
3	Insert the Class 4 TT and operate gearbox to verify smooth and correct operation.
4	Put the gearbox in vertical position with the Class 4 interface up. Verify that the compensation hose is oil filled. Evacuate any air if present.

#### 3.2. OPERATION

ID	Description
1	<b>Grab the gearbox'</b> D-handle and use the manipulator to install the gearbox into the correct Class 5 intervention bucket. The gearbox can be used in both vertical and horizontal orientation. The gearbox is held in position by gravity/friction, thus no locking mechanism to be engaged. Alignment of output socket may be necessary for fully insertion.
2	Insert the Class 4 TT and slowly operate in required direction in order to align the gearbox' output socket with the Class 5 interface. In vertical orientation, the gearbox will drop into final position once aligned. For horizontal orientation, the ROV must apply a gentle push during the alignment.
3	Perform intervention as required for the application.
4	When operation has been completed, remove the Class 4 TT.
5	Grab the D-handle and pull the gearbox out of the Class 5 interface bucket.



#### 3.3. PRE-OPERATION

The following actions shall be taken once the gearbox has been recovered to deck.

ID	Description
1	Hose down the gearbox using fresh water.
2	Check for damages, special attention to be made to input and output interfaces.
3	Put the tool in vertical orientation and verify that the compensation hose is completely oil-filled. Refill if required.
4	Insert the Class 4 TT and operate the gearbox to verify correct and smooth operation.
5	Wipe off any water and install the gearbox in dedicated transport box.



### 4. MAINTENANCE

### 4.1. YEARLY MAINTEANCE

ID	Description	
1	Check gearbox for damages, special attention to be made to input and output interfaces.	
2	Check coating, touch-up if required.	
3	Remove the plastic protection plate inside the class 4 bucket and pull out the compensation hose. Remove the end- plug from the hose.	
4	Unscrew BSP plug (item 27) at the input stem. Remove plug inserted in the compensation hose to allow draining. Check oil for contamination, debris, water etc.	
5	Put the tool in vertical position with the Cl4 interface upwards. Connect an oil- pump to the compensation hose and pump oil until it bleeds out of the BSP port. Reinstall the BSP plug.	Gear-oil: Q8 T 65 75W-90
6	Check for bubbles of air in compensation hose. Use vacuum pump to evacuate any trapped air and refill oil if required.	
7	Disconnect the oil-pump and reinstall the plug for the compensation hose.	



#### 4.2. 2-YEARLY MAINTEANCE

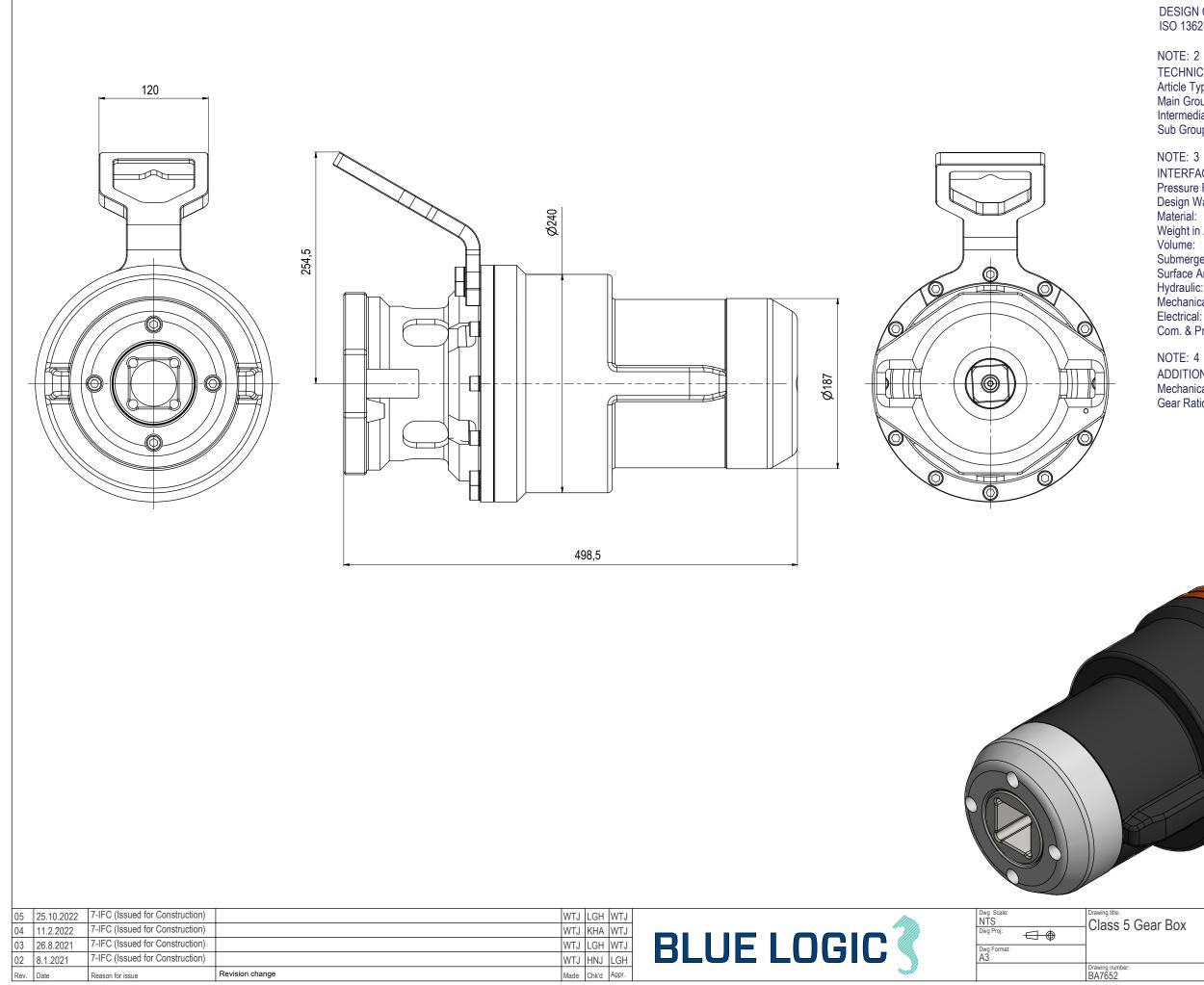
If the gearbox has been in operation for 2 years, it should be returned to Blue Logic for full inspection and maintenance.

ID	Description	
1	Check gearbox for damages, special attention to be made to input and output interfaces.	
2	Check coating, touch-up if required.	
3	Drain all oil through the BSP port. Inspect oil for water, debris etc.	
4	Open gearbox and perform a full inspection of all internal parts, gears etc. Replace parts and seals if required.	
5	Assemble gearbox and fill with oil.	Gear-oil: Q8 T 65 75W-90
6	Perform function test to verify full functionality.	



## APPENDIX 1 DRAWINGS

BA7652	Class 5 Gear Box
BB2406	Gear Box Cl. 5 Arrangement (Kit)



NOTE: 1 DESIGN CODE: ISO 13628-8 (E)

NOTE: 2 TECHNICAL CLASSIFICATION: 008-Actuation Article Type: Main Group: 8.02. ISO-5 Actuation Intermediate Group: 8.45.03. Gear Sub Group: 8.45.127.02. Intervention

INTERFACE INFORMATION: Pressure Rating Bar: 300 Design Water Depth: 3000m Material: N/A Weight in Air: 41,4 kg Volume: 12,51 dm^3 Submerged Weight: 28,55 kg Surface Area: 26970 cm^2 Hydraulic: N/A ISO Class 4 Input, ISO Class 5 Output Mechanical: Electrical: N/A N/A Com. & Protocol:

ADDITIONAL INFORMATION: Mechanical Gear Box with ISO Class 5 Output. Gear Ratio 10kNm 1:3,78

01 Rev.	3.5.2022 Date	7-IFC (Issued for Construction) Reason for issue	Revision change	WTJ KHA WTJ Made Chk'd Appr.	BLUE LOGIC	Dwg Scale: NTS Dwg Proj: Dwg Format: A3 Drawing number Drawing number Drawing number Drawing number Drawing title: Gear E Drawing number BB2406

NOTE: 1 STANDARDS: ISO 13628-8 / API 17H

NOTE: 2INTERFACE INFORMATION:Hydraulic:N/AMechanical:ISO Class 4 input / ISO Class 5 outputElectrical:N/AData Com.:N/A

NOTE: 3	
PROPERTIES:	
Material Class:	N/A
Temperature Class:	N/A
Rated Work Press Bar:	300
Test Pressure:	N/A
Specification Level:	N/A
Flow Rate:	N/A
Qualification:	N/A
Application:	ISO Class 5
Load Rating:	N/A
Torque Rating:	6 750Nm
Design Water Depth:	3000m
Weight in Air:	60,8 kg
Volume:	127,84 dm^3
Submerged Weight:	-70,28 kg

NOTE: 4 ADDITIONAL INFORMATION: Mechanical Gear Box with ISO Class 4 input and ISO Class 5 output. Maximum torque 6 750kNm. Gear ratio 2,5:1

## r Box Cl. 5 Arrangement