

DOCUMENT TITLE:Operation & Maintenance Manual for Class 5 GearboxPROJECT TITLE:8.2. ISO-5-Mech.InterfacesPROJECT:600145DOCUMENT NUMBER:600145-TD-0002REV:01NUMBER OF PAGES:12DATE:04.05.2023

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OBJECTIVE

The objective of this document is to present a comprehensive technical description of the Blue Logic Class 5 Gearbox. Relevant technical aspects for information and familiarization are covered as well as detailed technical data. For further information reference is made to drawing BA7652 Class 5 Gearbox.

ABSTRACT

The Blue Logic Gear Box CI. 5 is designed in accordance with ISO/API, and the purpose is to enable operation of equipment with Class 5 interface using a torque tool with Class 4 output interface.

REVISION CHANGE/RECORD

| REV | REASON FOR REVISION/ DESCRIPTION OF CHANGES | | |
|-----|---|--|--|
| 01 | Issued for Use | | |
| | | | |
| | | | |



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1. INTRODUCTION

The Class 5 Gearbox is designed to enable operation of Class 5 interfaces using a Class 4 torque tool for maximum flexibility at minimum cost.

The gearbox can be delivered as a complete kit, BB2406, including required components to adapt the tool to the interfaces as described above.

The Gearboxes are available as 6,7kNm (standard version) and 10,8kNm versions.

1.1. DOCUMENT USE

This document shall be used as a general information for all aspects related to safe use, installation, removal, maintenance, and storage of the Class 5 Gearbox.

1.2. REFERENCES

Latest version of the following documents

| ld. | Doc. No | Originator | Document Title |
|------|---------|------------|----------------------------------|
| /01/ | BA7652 | Blue Logic | Class 5 Gear Box |
| /02/ | BB2406 | Blue Logic | Gear Box Cl. 5 Arrangement (Kit) |

1.3. ABBREVIATIONS

| ROV | Remotely Operated Vehicle | | | |
|-----|---------------------------|--|--|--|
| HPU | Hydraulic Power Unit | | | |
| FAT | Factory Acceptance Test | | | |
| TT | Torque Tool | | | |



2. TECHNICAL DESCRIPTION

2.1. GENERAL

The gearbox is designed to be a compact tool with low submerged weight to enable efficient ROV intervention. As base case, the gearbox is intended to be used as a stand-alone unit for installation in Class 5 interfaces. Once installed, the Class 4 torque tool, hereafter referred to as TT, shall be inserted in the Class 4 interface of the gearbox. The unit is then ready for operation.

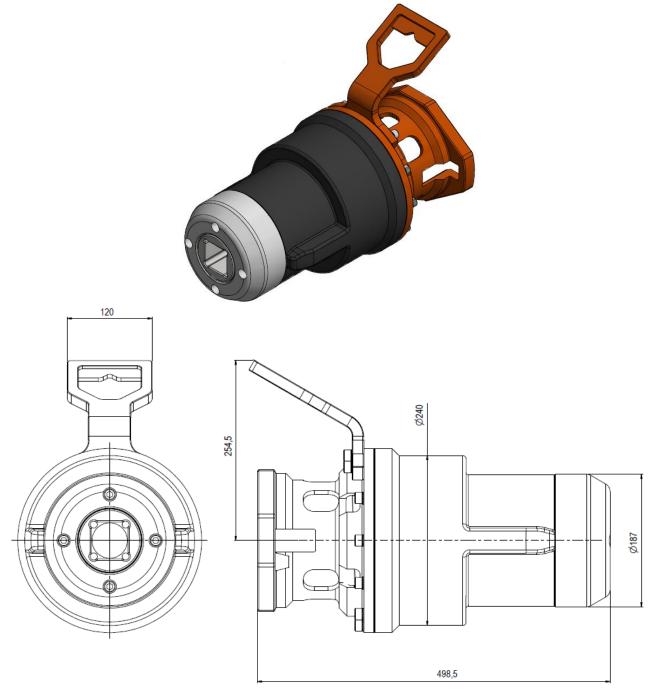
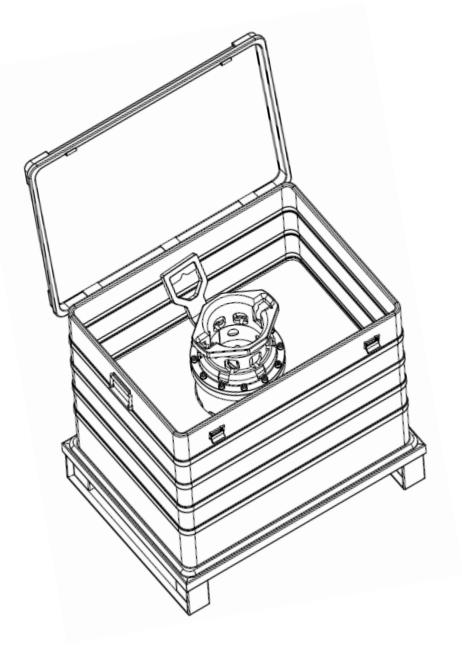
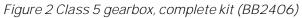


Figure 1, Cl.5 gearbox

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The gearbox is delivered in a transport box, containing required accessories and spares.



2.2. INTERFACES

2.2.1. Mechanical Interface Torque Input:

- ISO/API Class 4

Torque Output:

- ISO/API Class 5

ROV Interface:

- ROV D-handle

2.2.2. Hydraulic Interface

The gearbox is all-mechanical, but the housing is pressure compensated using an oil-filled ½" Tygon compensator hose. Blind fitting at the end of the hose to be pulled out for filling/draining of compensation hose. Make sure to evacuate all air when filling with oil. Gear-oil: Q8 T 65 75W-90.

2.3. MATERIAL SELECTION

The gearbox is mainly constructed in anodized Aluminium, and designed for intervention, i.e. not permanent installation

2.4. TECHNICAL DATA

| Overall dimensions | Ø260 x 499 mm |
|-------------------------------|----------------|
| Weight in air | 41,4 kg |
| Weight in water | 28,6 kg |
| Pressure rating | 300 bar |
| Max water depth | 3 000 m |
| Max output, gear ratio 1:2,5 | 6,7 kNm |
| Max output, gear ratio 1:3,78 | 10 kNm |
| Gear-oil | Q8 T 65 75W-90 |



3. OPERATION

3.1. PREPARATIONS

Prior to operation, the following actions shall be carried out.

| ID | Description |
|----|---|
| 1 | Check the gearbox for damages. |
| 2 | Verify correct output interface selected. Replace output interface if required, ref. section 3.4. |
| 3 | Insert the Class 4 TT and operate gearbox to verify smooth and correct operation. |
| 4 | Put the gearbox in vertical position with the Class 4 interface up. Verify that the compensation hose is oil filled. Evacuate any air if present. |

3.2. OPERATION

| ID | Description |
|----|--|
| 1 | Grab the gearbox' D-handle and use the manipulator to install the gearbox into the correct Class 5 intervention bucket. The gearbox can be used in both vertical and horizontal orientation. The gearbox is held in position by gravity/friction, thus no locking mechanism to be engaged. Alignment of output socket may be necessary for fully insertion. |
| 2 | Insert the Class 4 TT and slowly operate in required direction in order to align the gearbox' output socket with the Class 5 interface. In vertical orientation, the gearbox will drop into final position once aligned. For horizontal orientation, the ROV must apply a gentle push during the alignment. |
| 3 | Perform intervention as required for the application. |
| 4 | When operation has been completed, remove the Class 4 TT. |
| 5 | Grab the D-handle and pull the gearbox out of the Class 5 interface bucket. |



3.3. PRE-OPERATION

The following actions shall be taken once the gearbox has been recovered to deck.

| ID | Description |
|----|--|
| 1 | Hose down the gearbox using fresh water. |
| 2 | Check for damages, special attention to be made to input and output interfaces. |
| 3 | Put the tool in vertical orientation and verify that the compensation hose is completely oil-filled. Refill if required. |
| 4 | Insert the Class 4 TT and operate the gearbox to verify correct and smooth operation. |
| 5 | Wipe off any water and install the gearbox in dedicated transport box. |



4. MAINTENANCE

4.1. YEARLY MAINTEANCE

| ID | Description | |
|----|---|--------------------------|
| 1 | Check gearbox for damages, special attention to be made to input and output interfaces. | |
| 2 | Check coating, touch-up if required. | |
| 3 | Remove the plastic protection plate inside the class 4 bucket and pull out the compensation hose. Remove the end- plug from the hose. | |
| 4 | Unscrew BSP plug (item 27) at the input stem. Remove plug inserted in the compensation hose to allow draining. Check oil for contamination, debris, water etc. | |
| 5 | Put the tool in vertical position with the Cl4 interface upwards. Connect an oil- pump to the compensation hose and pump oil until it bleeds out of the BSP port. Reinstall the BSP plug. | Gear-oil: Q8 T 65 75W-90 |
| 6 | Check for bubbles of air in compensation hose. Use vacuum pump to evacuate any trapped air and refill oil if required. | |
| 7 | Disconnect the oil-pump and reinstall the plug for the compensation hose. | |



4.2. 2-YEARLY MAINTEANCE

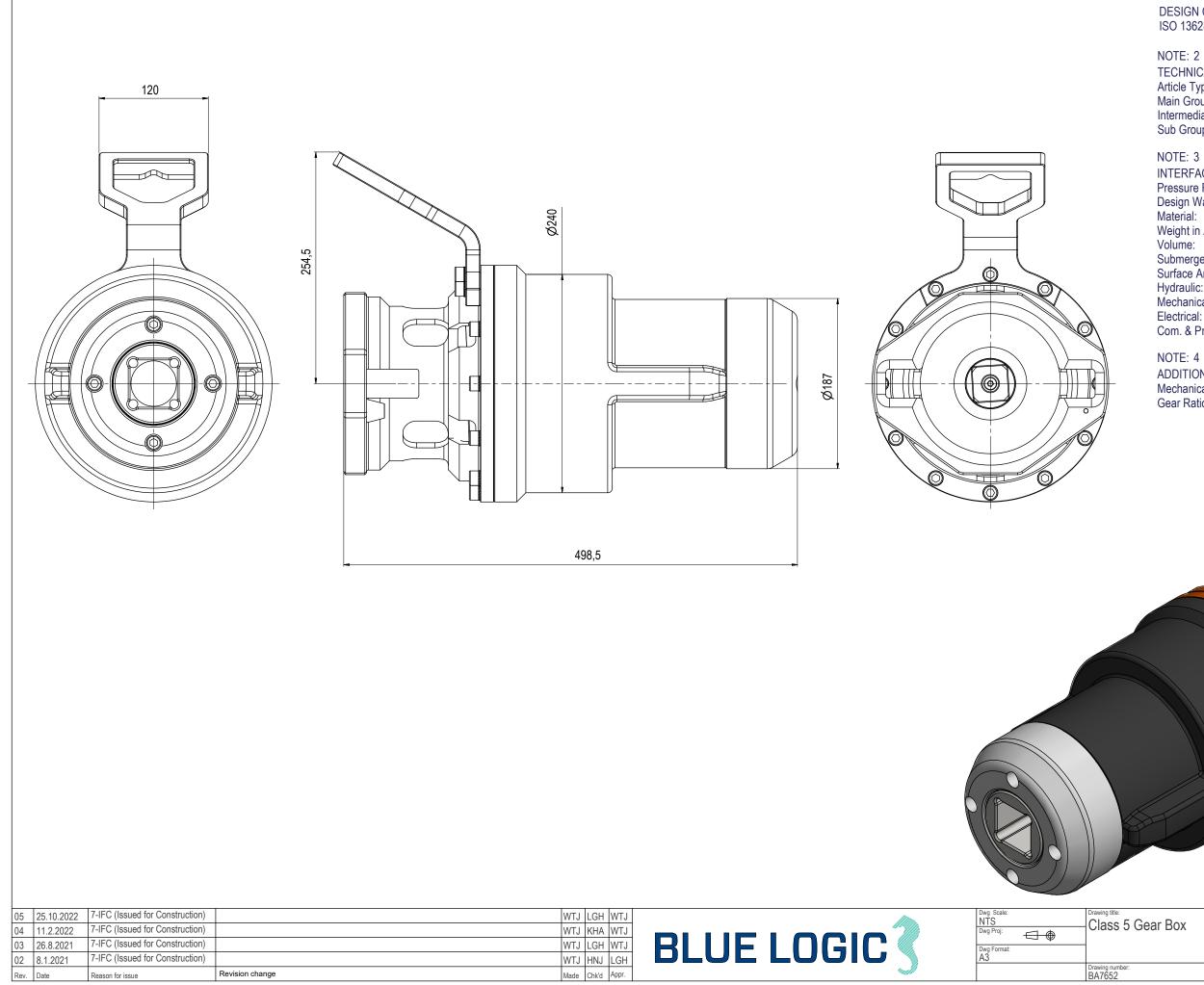
If the gearbox has been in operation for 2 years, it should be returned to Blue Logic for full inspection and maintenance.

| ID | Description | |
|----|---|--------------------------|
| 1 | Check gearbox for damages, special attention to be made to input and output interfaces. | |
| 2 | Check coating, touch-up if required. | |
| 3 | Drain all oil through the BSP port. Inspect oil for water, debris etc. | |
| 4 | Open gearbox and perform a full inspection of all internal parts, gears etc. Replace parts and seals if required. | |
| 5 | Assemble gearbox and fill with oil. | Gear-oil: Q8 T 65 75W-90 |
| 6 | Perform function test to verify full functionality. | |



APPENDIX 1 DRAWINGS

| BA7652 | Class 5 Gear Box |
|--------|----------------------------------|
| BB2406 | Gear Box Cl. 5 Arrangement (Kit) |



NOTE: 1 DESIGN CODE: ISO 13628-8 (E)

NOTE: 2 TECHNICAL CLASSIFICATION: 008-Actuation Article Type: Main Group: 8.02. ISO-5 Actuation Intermediate Group: 8.45.03. Gear Sub Group: 8.45.127.02. Intervention

INTERFACE INFORMATION: Pressure Rating Bar: 300 Design Water Depth: 3000m Material: N/A Weight in Air: 41,4 kg Volume: 12,51 dm^3 Submerged Weight: 28,55 kg Surface Area: 26970 cm^2 Hydraulic: N/A ISO Class 4 Input, ISO Class 5 Output Mechanical: Electrical: N/A N/A Com. & Protocol:

ADDITIONAL INFORMATION: Mechanical Gear Box with ISO Class 5 Output. Gear Ratio 10kNm 1:3,78

| 01 Rev. | 3.5.2022 Date | 7-IFC (Issued for Construction) Reason for issue | Revision change | WTJ KHA WTJ Made Chk'd Appr. | BLUE LOGIC | Dwg Scale: NTS Dwg Proj: Dwg Format: A3 Drawing number Drawing number Drawing number Drawing number Drawing title: Gear E Drawing number BB2406 |
|------------|------------------|---|-----------------|---------------------------------|------------|---|

NOTE: 1 STANDARDS: ISO 13628-8 / API 17H

NOTE: 2INTERFACE INFORMATION:Hydraulic:N/AMechanical:ISO Class 4 input / ISO Class 5 outputElectrical:N/AData Com.:N/A

| NOTE: 3 | |
|-----------------------|-------------|
| PROPERTIES: | |
| Material Class: | N/A |
| Temperature Class: | N/A |
| Rated Work Press Bar: | 300 |
| Test Pressure: | N/A |
| Specification Level: | N/A |
| Flow Rate: | N/A |
| Qualification: | N/A |
| Application: | ISO Class 5 |
| Load Rating: | N/A |
| Torque Rating: | 6 750Nm |
| Design Water Depth: | 3000m |
| Weight in Air: | 60,8 kg |
| Volume: | 127,84 dm^3 |
| Submerged Weight: | -70,28 kg |

NOTE: 4 ADDITIONAL INFORMATION: Mechanical Gear Box with ISO Class 4 input and ISO Class 5 output. Maximum torque 6 750kNm. Gear ratio 2,5:1

r Box Cl. 5 Arrangement